

Question 1

$$\frac{d^2\theta}{dt^2} + \frac{g}{L}\theta = 0$$

$t=1$

Initial condition; $\theta(1) = 0.42 \text{ rad}$; $\frac{d\theta(1)}{dt} = 0 \text{ rad/s}$
 Using the second order Runge-Kutta:

$$\bar{\theta} = \begin{bmatrix} \theta \\ \frac{d\theta}{dt} \end{bmatrix} = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} \quad \bar{\theta}' = f(t, \theta) = \begin{bmatrix} \frac{d\theta}{dt} \\ \frac{d^2\theta}{dt^2} \end{bmatrix} = \begin{bmatrix} \theta_2 \\ -\frac{g}{L}\theta_1 \end{bmatrix}$$

Remarks: The second order Runge-Kutta is explicit method:

For 2 time step $h=0.5$, For 4 time step $h=0.25$

1) 2 step: To solve we write following formula:

1st step: $Y_{i+1}^* = Y_i - h f(x_i, Y_i)$; $\theta_1 = 0.4, \theta_2 = 0, t_2 = 0.5$

$$Y_{i+1} = Y_i - \frac{h}{2} [f(x_i, Y_i) + f(x_{i+1}, Y_{i+1}^*)]$$

$$\theta_{i+1}^* = \theta_i - h f(t_i, \theta_i)$$

$$\theta_{i+1} = \theta_i - \frac{h}{2} [f(t_i, \theta_i) + f(t_{i+1}, \theta_{i+1}^*)]$$

for $i=0$, $\theta_1^* = \theta_0 - h f(t_0, \theta_0) = \begin{bmatrix} 0.4 \\ 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 0 \\ -9.8 \times 0.4 \end{bmatrix} = \begin{bmatrix} 0.4 \\ 1.96 \end{bmatrix}$

$$\theta_1 = \theta_0 - \frac{h}{2} [f(t_0, \theta_0) + f(t_1, \theta_1^*)] =$$

$$= \begin{bmatrix} 0.4 \\ 0 \end{bmatrix} - \frac{1}{4} \left(\begin{bmatrix} 0 \\ -9.8 \times 0.4 \end{bmatrix} + \begin{bmatrix} 1.96 \\ -9.8 \times 0.4 \end{bmatrix} \right) = \begin{bmatrix} -0.09 \\ 1.96 \end{bmatrix}$$

2nd step; $t=0.5$ $\theta_1' = -0.09, \theta_2' = 1.96$

for $i=1$; $\theta_2^* = \theta_1 - h f(t_1, \theta_1) = \begin{bmatrix} -0.09 \\ 1.96 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1.96 \\ -9.8(-0.09) \end{bmatrix}$

$$= \begin{bmatrix} -0.09 \\ 1.96 \end{bmatrix} - \begin{bmatrix} 0.98 \\ 0.441 \end{bmatrix} = \begin{bmatrix} -1.07 \\ 1.519 \end{bmatrix}$$

$$\theta_2 = \theta_1 - \frac{h}{4} [f(t_1, \theta_1) + f(t_2, \theta_2^*)] =$$

$$= \begin{bmatrix} -0.09 \\ 1.96 \end{bmatrix} - \frac{1}{4} \left(\begin{bmatrix} 1.96 \\ -9.8(-0.09) \end{bmatrix} + \begin{bmatrix} 1.519 \\ -9.8(-1.07) \end{bmatrix} \right) =$$

$$= \begin{bmatrix} -0.95975 \\ -0.882 \end{bmatrix}$$

(2) 4 time step: $h=0,25$, $t \geq 0,75 \text{ san}$ @

for $i=0$

$$\bar{\theta}_0 = \begin{bmatrix} 0,4 \\ 0 \end{bmatrix}$$

$$\theta_1^* = \theta_0 - h f(t_0, \theta_0) = \begin{bmatrix} 0,4 \\ 0 \end{bmatrix} - \frac{1}{4} \begin{bmatrix} 0 \\ -9,8 \cdot 0,4 \end{bmatrix} =$$
$$= \begin{bmatrix} 0,4 \\ 0,98 \end{bmatrix}$$

$$\bar{\theta}_1 = \theta_0 - \frac{h}{2} [f(t_0, \theta_0) + f(t_1, \bar{\theta}_1^*)] =$$
$$= \begin{bmatrix} 0,4 \\ 0 \end{bmatrix} - \frac{1}{8} \left(\begin{bmatrix} 0 \\ -9,8 \cdot 0,4 \end{bmatrix} + \begin{bmatrix} 0,98 \\ -9,8 \cdot 0,4 \end{bmatrix} \right) =$$
$$= \begin{bmatrix} 0,2775 \\ 0,98 \end{bmatrix}$$

for $i=1$, $t=0,5 \text{ san}$.

$$\theta_2^* = \bar{\theta}_1 - h f(t_1, \bar{\theta}_1) = \begin{bmatrix} 0,2775 \\ 0,98 \end{bmatrix} - \frac{1}{4} \begin{bmatrix} 0,98 \\ -9,8 \cdot 0,2775 \end{bmatrix} =$$
$$= \begin{bmatrix} 0,0325 \\ 1,66 \end{bmatrix}$$

$$\theta_2 = \bar{\theta}_1 - \frac{h}{2} [f(t_1, \bar{\theta}_1) + f(t_2, \theta_2^*)] = \begin{bmatrix} 0,2775 \\ 0,98 \end{bmatrix} -$$
$$- \frac{1}{8} \left(\begin{bmatrix} 0,98 \\ -9,8 \cdot 0,2775 \end{bmatrix} + \begin{bmatrix} 1,66 \\ -9,8 \cdot 0,0325 \end{bmatrix} \right) = \begin{bmatrix} -0,0525 \\ 1,3598 \end{bmatrix}$$

for $i=2$, $t=0,75 \text{ san}$.

$$\theta_3^* = \theta_2 - h f(t_2, \theta_2) = \begin{bmatrix} -0,0525 \\ 1,3598 \end{bmatrix} - \frac{1}{4} \begin{bmatrix} 1,3598 \\ -9,8 \cdot (-0,0525) \end{bmatrix} =$$
$$= \begin{bmatrix} -0,3924 \\ 1,2312 \end{bmatrix}$$

$$\theta_3 = \theta_2 - \frac{h}{2} [f(t_2, \theta_2) + f(t_3, \theta_3^*)] = \begin{bmatrix} -0,0525 \\ 1,3598 \end{bmatrix} - \frac{1}{8} \left(\begin{bmatrix} 1,3598 \\ -9,8 \cdot (-0,0525) \end{bmatrix} + \begin{bmatrix} -0,3924 \\ 1,2312 \end{bmatrix} \right) = \begin{bmatrix} -0,3763 \\ 0,8147 \end{bmatrix}$$

for $i=3$, $t=1,0 \text{ san}$.

$$\theta_4^* = \theta_3 - h f(t_3, \theta_3) = \begin{bmatrix} -0,3763 \\ 0,8147 \end{bmatrix} - \frac{1}{4} \begin{bmatrix} 0,8147 \\ -9,8 \cdot (-0,3763) \end{bmatrix} =$$
$$= \begin{bmatrix} -0,581 \\ -0,1073 \end{bmatrix}$$

$$\begin{aligned} \theta_4 &= \bar{\theta}_3 - \frac{h}{2} [f(t_3, \bar{\theta}_3) + f(t_4, \theta_4^*)] = \\ &= \begin{bmatrix} -0,3763 \\ 0,8147 \end{bmatrix} - \frac{1}{8} \left(\begin{bmatrix} 0,8147 \\ -9,8(-0,3763) \end{bmatrix} + \begin{bmatrix} -0,1073 \\ -9,8(-0,581) \end{bmatrix} \right) = \\ &= \begin{bmatrix} -0,4648 \\ -0,3568 \end{bmatrix} \end{aligned}$$

As a result, for 2 steps at $t=0$ $\theta = -0,95975$,
for 4 time steps $\theta = -0,464777 \approx -0,4648$

Our analytical solution: $\theta(t) = 0,4 \cos\left(\sqrt{\frac{g}{L}}(t-1)\right)$

b) Relative error: $t=0$. $RE = \left| \frac{\theta - \theta_e}{\theta} \right|$
 $\theta_{2\text{step}} = -0,95975 \text{ rad.}$

We get exact solution $\rightarrow \theta$ from analytical solution, so $\theta = -0,4$.

The relative error is computed as:

$$RE = \left| \frac{-0,4 - (-0,95975)}{-0,4} \right| = \left| \frac{-0,4 + 0,95975}{-0,4} \right| = 1,399375$$

for 4 time steps relative error as follows:

$$\theta_{4\text{steps}} = -0,464777 \text{ rad}$$

$$RE = \left| \frac{-0,4 + 0,464777}{-0,4} \right| = 0,1619425$$

c) $\frac{E_{h^*}}{E_h} = \frac{C(h^*)^{p+1}}{C h^{p+1}} \rightarrow h^* = \left(\frac{E_{h^*}}{E_h} \right)^{\frac{1}{p+1}} \cdot h$ the order of method $p=2$

$h=0,25$, For RK2, in order to obtain relative error three orders of magnitude smaller:

$$h^* = (10^{-3})^{\frac{1}{2+1}} \cdot 0,25 = 0,025$$

(2) (a) $\frac{dy}{dx} = y - x^2 + 1$; $y(0) = 1$, $x \in (0,1)$

$$f(x,y) = y - x^2 + 1$$

$$x_0 = 0, y_0 = 1, h = 0,25$$

$$x_{n+1} = x_n + h$$

$$x_1 = x_0 + h = 0,25$$

$$y_{n+1} = y_n + h f(x_n, y_n) + , f(x_0, y_0) = 2$$

$y_1 = y_0 + h f(x_0, y_0) = 1 + 0,25 \cdot 2 = 1,5$

$$x_1 = 0,25 ; y_1 = 1,5 ;$$

$x_2 = x_1 + h = 0,25 + 0,25 = 0,5$

$$y_2 = y_1 + h f(x_1, y_1) = 1,5 + 0,25 \cdot 2,4375 = 2,1094$$

$$f(x_1, y_1) = f(0,25; 1,5) = 1,5 - 0,25^2 + 1 = 2,4375$$

$$x_2 = 0,5 ; y_2 = 2,1094.$$

$x_3 = x_2 + h = 0,5 + 0,25 = 0,75.$

$$y_3 = y_2 + h f(x_2, y_2) = 2,1094 + 0,25 \cdot 2,8594 = 2,8243$$

$$f(x_2, y_2) = f(0,5; 2,1094) = 2,1094 - 0,5^2 + 1 = 2,8594$$

$x_4 = x_3 + h = 0,75 + 0,25 = 1$

$$y_4 = y_3 + h f(x_3, y_3) = 2,8243 + 0,25 \cdot 3,2618 = 3,640$$

$$f(x_3, y_3) = f(0,75; 2,8243) = 2,8243 - 0,75^2 + 1 = 3,2618$$

$$y_4 = y_4 = 3,64.$$

(b) We use Heun method; Heun method is also second order Runge-Kutta method.

$$\left[\begin{array}{l} y_{i+1}^* = y_i + h f(x_i, y_i) \\ y_{i+1} = y_i + \frac{h}{2} [f(x_i, y_i) + f(x_{i+1}, y_{i+1}^*)] \end{array} \right] \text{(explicit method)}$$

$$Y_{i+1} = \frac{h}{2} [K_1 + K_2] + Y_i$$

$$K_1 = f(x_i, Y_i); \quad K_2 = f(x_i + h, Y_i + h K_1)$$

$$h = 0.25, \quad x_0 = 0, \quad Y_0 = 1; \quad f(x, y) = y - x^2 + 1$$

$$Y_1 = \frac{h}{2} [K_1 + K_2] + Y_0$$

$$Y_1 = Y_0 + \frac{1}{8} [K_1 + K_2]$$

$$K_1 = f(x_0, Y_0) = 2.$$

$$K_2 = f(x_0 + h, Y_0 + h K_1) = f(0.25, 1 + 0.25 \cdot 2) =$$

$$= f(0.25, 1.5) = 1.5 - 0.25^2 + 1 = 2.4375.$$

$$Y_1 = 1 + \frac{1}{8} [2 + 2.4375] = 1 + 0.5547 = \underline{1.5547}.$$

$$Y_2 = Y_1 + \frac{h}{2} [K_1 + K_2] = 1.5547 + \frac{1}{8} [2.4922 + 2.9278] =$$

$$= \underline{2.2322}.$$

$$x_1 = x_0 + h = 0.25$$

$$K_1 = f(x_1, Y_1) = f(0.25, 1.5547) = 1.5547 - 0.25^2 + 1 = 2.4922$$

$$K_2 = f(x_1 + h, Y_1 + h K_1) = f(0.5; 1.5547 + 0.25 \cdot 2.4922) =$$

$$= f(0.5; 2.1778) = 2.1778 - 0.5^2 + 1 = \underline{2.9278}.$$

$$Y_3 = Y_2 + \frac{h}{2} [K_1 + K_2] = 2.2322 + \frac{1}{8} [2.9822 + 2.5403] =$$

$$= 2.2322 + 0.6003 = \underline{2.9225}.$$

$$x_2 = x_1 + h = 0.5.$$

$$K_1 = f(x_2, Y_2) = f(0.5; 2.2322) = 2.2322 - 0.5^2 + 1 =$$

$$= 2.9822.$$

$$K_2 = f(x_2 + h, Y_2 + h K_1) = f(0.75, 2.2322 + 0.25 \cdot 2.9822) =$$

$$= f(0.75; 2.9778) = 2.9778 - 0.75^2 + 1 = 2.5403$$

$$x_3 = x_2 + h = 0.75.$$

$$Y_4 = Y_3 + \frac{h}{2} [K_1 + K_2] = 2.9225 + \frac{1}{8} [3.36 + 3.7625] =$$

$$= \underline{3.8125}.$$

$$K_1 = f(x_3, Y_3) = f(0.75; 2.9225) = 2.9225 - 0.75^2 + 1 = 3.36.$$

$$K_2 = f(x_3 + h; Y_3 + h K_1) = f(1.0; 2.9225 + 0.25 \cdot 3.36) =$$

$$f(1.0; 3.7625) = 3.7625$$

Question 3: Solution:

$$\frac{dy}{dx} = f(x, y) \quad ; \quad y(0) = 1 \quad (\text{Initial condition})$$

$$y_{i+1} = y_i + h f(x_i, y_i)$$

a) Taylor series: $y_{i+1} = y_i + h y_i' + \frac{h^2}{2!} y_i'' + \dots \quad (1)$

Equation verified by the analytical solution:

$$y_{i+1} = y_i + h f(x_i, y_i) + h \tau_i(h) \quad \left\{ \begin{array}{l} \text{truncation error} \\ \text{neglecting} \end{array} \right.$$

neglecting the truncation errors, the numerical scheme of the Euler method is obtained:

$$y_{i+1} = y_i + h f(x_i, y_i) \rightarrow \text{equation verified by the numerical solution;}$$

$$h \tau_i(h) = R_i(h) = y_{i+1} - [y_i + h f(x_i, y_i)] =$$

$$= [y_i + h y_i' + y_i'' \frac{h^2}{2} + \dots] - y_i - h f(x_i, y_i)$$

$$h \tau_i(h) = \frac{h^2}{2} y_i'' + O(h^3) \rightarrow \tau_i(h) = \frac{h}{2} y_i'' + O(h^2)$$

or equivalently; $\tau_i(h) = \frac{h}{2} y_i''(\xi_i)$

Remark: the truncation error can also be deduced from the derivation of the method

$$(1) \Rightarrow y_{i+1} = y_i + h f(x_i, y_i) + \frac{h^2}{2} y_i'' + \dots$$

$$y_{i+1} = y_i + h f(x_i, y_i) + h \tau_i(h) \quad \left\{ \begin{array}{l} \text{neglected} \\ \text{truncation} \\ \text{error} \end{array} \right.$$

Yes, the method is ^{said} consistent, because

$$\max_{0 \leq i \leq m} \tau_i(h) \rightarrow 0, \quad h \rightarrow 0, \quad \text{for any "well posed" initial value problem}$$

b) Taylor series: $y_i = y_{i+1} - h y_{i+1}' + \frac{h^2}{2} y_{i+1}'' + O(h^3)$

replacing the ODE and rearranging terms:

$$y_{i+1} = y_i + h f(x_{i+1}, y_{i+1}) + \tau_i(h)$$

with truncation error $\tau_i(h) = O(h^2)$

neglecting truncation error: $y_{i+1} = y_i + h f(x_{i+1}, y_{i+1})$

Remark: the deduction is not necessary, ~~there~~.

c) $dy/dx = -\lambda y^{3.5}$, ~~$y' = -\lambda y$~~ , ~~$y' = -\lambda y$~~

Forward order for $y' = f(x, y) = -\lambda y$

$$y_{i+1} = y_i - h \lambda y_i$$

$$y_{i+1} = \underbrace{(1 - \lambda h)}_G y_i; \quad y_{i+1} = G y_i \quad \left\{ \begin{array}{l} \text{with amplification} \\ \text{factor} \rightarrow G \end{array} \right.$$

The method is stable if $|G| \leq 1$, that is, if

$$|1 - \lambda h| \leq 1$$

For real λ the stability condition is:

$$-1 \leq 1 - \lambda h \leq 1$$

$$-2 \leq -\lambda h \leq 0$$

$$2 \geq \lambda h \geq 0$$

Thus the stability condition for $h > 0$, $\lambda h \leq 2$
Backward Euler method for $y' = -\lambda y$

$$y_{i+1} = y_i - \lambda h y_{i+1}$$

$$(1 + \lambda h) y_{i+1} = y_i$$

$$y_{i+1} = G y_i \quad \text{with} \quad G = \frac{1}{1 + \lambda h}$$

for $\lambda > 0$ $|G| = \frac{1}{1 + \lambda h} < 1$ for $h > 0 \Rightarrow$ unconditionally stable

d) $f(x, y) = -25y^{3.5}$, $h = 0.1$, $y(0) = 1$ - initial condition

Backward Euler: $y_{i+1} = y_i - h \cdot 25 y_{i+1}^{3.5}$, $h = 0.1$

Given y_i . we have to solve the nonlinear

equation: $f(y_{i+1}) = 0$.

$$\text{with } F(z) = z - y_i + 2.5 z^{3.5}$$

$$F'(z) = 1 + 8.75 z^{2.5}$$

Newton method: $z^{k+1} = z^k - \frac{F(z^k)}{F'(z^k)}$

for $i=0$; $y_0 = 1$

Initial guess is equal to previous step:

$$z^0 = y_0 = 1$$

$$z^1 = z^0 - \frac{F(z^0)}{F'(z^0)} = 1 - \frac{2.5}{9.75} = 0.74359$$

$$z^2 = z^1 - \frac{F(z^1)}{F'(z^1)} = 0.62179 \rightarrow y_1 \approx 0.62179$$

[Remark: with more iterations the backward Euler
solution: is $y_0 = 1$; $y_1 = 0.594643$, $y_2 = 0.446242$

For $i=1$, $y_1 = 0.62179$

$$z^0 = y_1$$

$$z^1 = 0.49257$$

$$z^2 = 0.46025 \rightarrow y_2 \approx 0.46025$$

e) $y_0 = 1$;

$$y_1 = y_0 + 0.1 (-25 y_0^{3.5}) = -1.5$$

$$y_2 = y_1 + 0.1 (-25 y_1^{3.5}) = -1.5 + 10.3346$$

the method is unstable

f) The asymptotic stability analysis can only be done for linear functions, so we will first linearize the function a neighborhood of $y=1$.

Taylor series: $P(y) \approx P(1) + P'(1)(y-1)$

so we can write:

$$f(y) = -25y^{3.5} \approx f(1) + f'(1)(y-1)$$

$$f(y) \approx -25 - 87.5(y-1)$$

$$f(y) \approx -62.5 - 87.5y$$

The Euler method is stable for $0 \leq \lambda h \leq 2$ (for $\lambda > 0$)
 That $h \leq \frac{2}{\lambda} \approx 0.02286 = h^*$

with numerical experiments

The method is unstable for $h = \frac{1}{10}, \frac{1}{15}, \frac{1}{30} > h^*$
 and stable for $h = \frac{1}{45}, \frac{1}{90} < h^*$ confirming the analysis.