

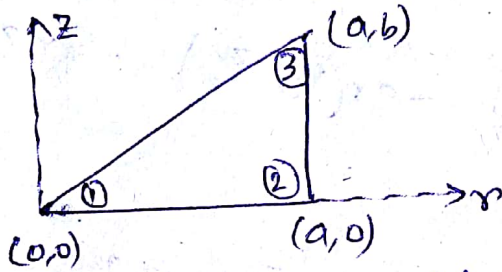
CSMD
Assignment-04

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①

4.1 // Given, for an axisymmetric triangle,

$$r_1=0, r_2=r_3=a, z_1=z_2=0, z_3=b$$



Material is isotropic with $\nu=0$

$$E = E \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1/2 \end{bmatrix}$$

We define linear shape functions, N_1, N_2 & N_3 as follows:-

$$N_1 = \frac{1}{2A} (f_1 + r b_1 + z c_1) \quad ; \quad N_2 = \frac{1}{2A} (f_2 + r b_2 + z c_2)$$

$$\& \quad N_3 = \frac{1}{2A} (f_3 + r b_3 + z c_3)$$

And,

$$\begin{array}{l|l|l} f_1 = r_2 z_3 - r_3 z_2 = ab - 0 = ab & b_1 = z_2 - z_3 = -b & c_1 = r_3 - r_2 = 0 \\ f_2 = r_3 z_1 - r_1 z_3 = 0 - 0 = 0 & b_2 = z_3 - z_1 = b & c_2 = r_1 - r_3 = -a \\ f_3 = r_1 z_2 - r_2 z_1 = 0 - 0 = 0 & b_3 = z_1 - z_2 = 0 & c_3 = r_2 - r_1 = a \end{array}$$

& $A = \frac{1}{2} ab$ [from geometry of triangle]

$$\therefore N_1 = 1 - r/a$$

$$N_2 = r/a - z/b$$

$$N_3 = z/b$$

②

Now, the stiffness matrix can be evaluated using a simple one point integration,

$$K = 2\pi \bar{r} A \bar{B} \bar{B}^T \quad \text{--- (2)}$$

where, $\bar{B} = \bar{B}(\bar{r}, \bar{z})$, (\bar{r}, \bar{z}) is the coordinate of the centroid of our elemental triangle.

$$\bar{r} = \frac{r_1 + r_2 + r_3}{3} = \frac{2}{3}a$$

$$\bar{z} = \frac{z_1 + z_2 + z_3}{3} = \frac{1}{3}b$$

\therefore From (1), we have (at the centroid),

$$N_1 = 1 - \frac{\bar{r}}{a} = 1 - \frac{(\frac{2}{3})a}{a} = \frac{1}{3}$$

$$N_2 = \frac{\bar{r}}{a} - \frac{\bar{z}}{b} = \frac{2}{3} - \frac{1}{3} = \frac{1}{3}$$

$$N_3 = \frac{\bar{z}}{b} = \frac{1}{3}$$

$$\text{Area of the triangle, } A = \frac{1}{2} \begin{vmatrix} r_1 & r_2 & r_3 \\ z_1 & z_2 & z_3 \\ 1 & 1 & 1 \end{vmatrix} = \frac{1}{2} \begin{vmatrix} 0 & a & a \\ 0 & 0 & b \\ 1 & 1 & 1 \end{vmatrix}$$

$$= \frac{1}{2} ab,$$

which can also be seen from the geometry.

$$\therefore \frac{2AN_1}{\bar{r}} = \frac{2AN_2}{\bar{r}} = \frac{2AN_3}{\bar{r}} = \frac{2 \times \frac{1}{2} ab \times \frac{1}{3}}{\frac{2}{3}a} = \frac{ab/3}{2a/3} = b/2$$

③

Now,

$$\bar{B}^T = \frac{1}{2A} \begin{bmatrix} b_1 & 0 & b_2 & 0 & b_3 & 0 \\ 0 & c_1 & 0 & c_2 & 0 & c_3 \\ \frac{2AN_1}{r} & 0 & \frac{2AN_2}{r} & 0 & \frac{2AN_3}{r} & 0 \\ c_1 & b_1 & c_2 & b_2 & c_3 & b_3 \end{bmatrix}$$

Substituting the values, we have,

$$\bar{B}^T = \frac{1}{2 \times (\frac{1}{2} ab)} \begin{bmatrix} -b & 0 & b & 0 & 0 & 0 \\ 0 & 0 & 0 & -a & 0 & a \\ b/2 & 0 & b/2 & 0 & b/2 & 0 \\ 0 & -b & -a & b & a & 0 \end{bmatrix}$$

∴ From (2), we get,

$$\begin{aligned} K &= 2\pi \bar{r} A \bar{B} E \bar{B}^T \\ &= 2\pi \frac{1}{2} (ab) \times \frac{2}{3} a \bar{B} E \bar{B}^T \\ &= \frac{2}{3} a^2 b \pi \bar{B} E \bar{B}^T \quad \text{--- (3)} \end{aligned}$$

Now,

$$\bar{B} E \bar{B}^T = \begin{bmatrix} -b & 0 & b/2 & 0 \\ 0 & 0 & 0 & -b \\ b & 0 & b/2 & -a \\ 0 & -a & 0 & b \\ 0 & 0 & b/2 & a \\ 0 & a & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1/2 \end{bmatrix} \begin{bmatrix} -b & 0 & b & 0 & 0 & 0 \\ 0 & 0 & 0 & -a & 0 & a \\ b/2 & 0 & b/2 & 0 & b/2 & 0 \\ 0 & -b & -a & b & a & 0 \end{bmatrix}$$

$$\textcircled{4} \quad = \frac{E}{4A^2} \begin{bmatrix} -b & 0 & b/2 & 0 \\ 0 & 0 & 0 & -b \\ b & 0 & b/2 & -a \\ 0 & -a & 0 & b \\ 0 & 0 & b/2 & a \\ 0 & a & 0 & 0 \end{bmatrix} \begin{bmatrix} -b & 0 & b & 0 & 0 & 0 \\ 0 & 0 & 0 & -a & 0 & a \\ b/2 & 0 & b/2 & 0 & b/2 & 0 \\ 0 & -b/2 & -a/2 & b/2 & a/2 & 0 \end{bmatrix}$$

$$= \frac{E}{4(1/2ab^2)} \begin{bmatrix} 5/4 b^2 & 0 & -3/4 b^2 & 0 & 1/4 b^2 & 0 \\ 0 & 1/2 b^2 & 1/2 ab & -1/2 b^2 & -1/2 ab & 0 \\ -3/4 b^2 & 1/2 ab & (5/4 b^2 + 1/2 a^2) & -1/2 ab & (1/4 b^2 - 1/2 a^2) & 0 \\ 0 & -1/2 b^2 & -1/2 ab & (1/2 b^2 + a^2) & 1/2 ab & -a^2 \\ 1/4 b^2 & 1/2 ab & (1/4 b^2 - 1/2 a^2) & 1/2 ab & (1/4 b^2 + 1/2 a^2) & 0 \\ 0 & 0 & 0 & -a^2 & 0 & a^2 \end{bmatrix} \text{symm}$$

Now, from (3) we have,

$$K = \frac{2/3 a^2 \cdot 6\pi \frac{E}{a^2 b^2}}{3b} = \frac{2\pi E}{3b} \begin{bmatrix} 5/4 b^2 & 0 & -3/4 b^2 & 0 & 1/4 b^2 & 0 \\ \dots & 1/2 b^2 & 1/2 ab & -1/2 b^2 & -1/2 ab & 0 \\ \dots & \dots & (5/4 b^2 + 1/2 a^2) & -1/2 ab & (1/4 b^2 - 1/2 a^2) & 0 \\ \dots & \dots & \dots & (1/2 b^2 + a^2) & 1/2 ab & -a^2 \\ \dots & \dots & \dots & \dots & (1/4 b^2 + 1/2 a^2) & 0 \\ \dots & \dots & \dots & \dots & \dots & a^2 \end{bmatrix} \text{symm}$$

5. The stiffness matrix equation takes the form -

$$K U = f$$

$$\Rightarrow \frac{2\pi E}{3b} \begin{bmatrix} 5/4 b^2 & 0 & -3/4 b^2 & 0 & 1/4 b^2 & 0 \\ \dots & 1/2 b^2 & 1/2 ab & -1/2 b^2 & -1/2 ab & 0 \\ \dots & \dots & (5/4 b^2 + 1/2 a^2) & -1/2 ab & (1/4 b^2 - 1/2 a^2) & 0 \\ \dots & \dots & \dots & (1/2 b^2 + a^2) & 1/2 ab & -a^2 \\ \dots & \dots & \dots & \dots & (1/4 b^2 + 1/2 a^2) & 0 \\ \dots & \dots & \dots & \dots & \dots & a^2 \end{bmatrix} \begin{bmatrix} U_{r1} \\ U_{z1} \\ U_{r2} \\ U_{z2} \\ U_{r3} \\ U_{z3} \end{bmatrix} = \begin{bmatrix} f_{r1} \\ f_{z1} \\ f_{r2} \\ f_{z2} \\ f_{r3} \\ f_{z3} \end{bmatrix}$$

(2)

Since the object is axisymmetric, for revolution the deformation will only be limited to radial direction (r).

Hence, $U_{z1} = U_{z2} = U_{z3} = 0$ in the above equation.

So, the rows & columns 2, 4 & 6 of 'K' must vanish.

But U_{r1}, U_{r2} & U_{r3} are not equal to zero, the ^{other} rows & columns must exist in the equation.

3/

The force vector can be expressed as follows -

$$f = \int_A N^T b r dA \quad \text{--- (4)}$$

$$\text{Now, } r = \sum_{i=1}^3 r_i N_i$$

$$= r_1 N_1 + r_2 N_2 + r_3 N_3$$

$$= r - \cancel{2a/b} + \cancel{2a/b}$$

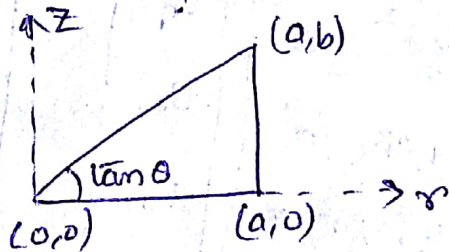
$$= r$$

⑥

Now, from (4),

$$f = \int \int_Z F dz dr, \quad F = N^T b r \quad \text{--- (5)}$$

Here, r varies from 0 to a as can be seen from the geometry of the triangular element.



From the geometry, we find the following relation between r & z -

$$z/r = \tan \theta = b/a$$

$$\Rightarrow z = br/a$$

$\therefore z$ varies from 0 to br/a .

Now,

$$F = N^T b r$$

$$= r \begin{bmatrix} (1-r/a) & 0 \\ (r/a - z/b) & 0 \\ z/b & 0 \\ 0 & 1-r/a \\ 0 & r/a - z/b \\ 0 & z/b \end{bmatrix} \begin{bmatrix} 0 \\ -q \end{bmatrix} \quad \begin{matrix} 2 \times 1 \\ 6 \times 2 \end{matrix}$$

$$= \begin{bmatrix} 0 & 0 & 0 & -gr(1-r/a) & -gr(r/a - z/b) & -grz/b \end{bmatrix}$$

∴ From (5),

$$f = \int_0^a \int_0^{br/a} \begin{bmatrix} 0 & 0 & 0 & -gr(1-r/a) & -gr(r/a - z/b) & -grz/b \end{bmatrix} dz dr \quad \text{--- (6)}$$

Integrating the above equation term by term we get.

$$\int_0^a \int_0^{br/a} -gr(1-r/a) dz dr = -\frac{ga^2b}{12}$$

$$\int_0^a \int_0^{br/a} -gr(r/a - z/b) dz dr = -\frac{gba^2}{8} \quad \text{, , \&}$$

$$\int_0^a \int_0^{br/a} -grz/b dz dr = -\frac{gba^2}{8}$$

$$\int_0^a \int_0^{br/a} 0 dz dr = 0 \quad \left[\because \text{definite integral of } 0 \text{ gives } 0 \right]$$

∴ From (6), we have

$$f = -\frac{ga^2b}{12} \begin{bmatrix} 0 & 0 & 0 & 1 & 3/2 & 3/2 \end{bmatrix} \text{ per unit density.}$$