

PERFECT K. MARENCA  
FEF FINAL EXAM.

- 1 a) Yes it is suitable because it passes the LBB condition.
- b) Yes it is suitable because it guarantees or enforces the positive definiteness of the final matrix obtained from the discrete equations.
- c) For DG method we can approximate the pressure with the same polynomial degree as the velocity and the element still fulfills the LBB condition.

The global size of the system :

- d) Global problem corresponds only to the red lines : 56 d.o.f.  
Local problem corresponds only to the black dots : 10 d.o.f.  
Velocity global : 56 d.o.f    pressure global (p) : 1 d.o.f.  
Velocity local : 10 d.o.f    pressure local : 10 d.o.f.

\* the above values corresponds only to one direction (x) for example as our problem is in 2D, if considering both direction we just double the number.

- e) Assemble and solve the global problem (loop on the elements and element faces)



loop on the element to solve the local problem



loop on the element to post process solution.

2 a) firstly rewriting the equation as follows.

$$u_t + k(u) + c(u) + R(u) + \nabla p = f$$

$$\nabla u = 0.$$

$$k(u) = -\nu \nabla^2 u$$

$$c(u) = (u \cdot \nabla) u$$

$$R(u) = \sigma u.$$

time discrete equation:

$$\frac{u^{n+1} - u^n}{\Delta t} + k(u^{n+1/2}) + c(u) + R(u^{n+1/2}) + \nabla p^{n+1} = f^{n+1}$$

$$\nabla \cdot u^{n+1} = 0$$

$$* c(u) = [(u \cdot \nabla) u]^{n+1/2}.$$

b) using bilinear & trilinear forms:

$$(w, \Delta u / \Delta t) + a(w, u^{n+1/2}) + c(u^{n+1/2}; w, u^{n+1/2}) + r(w, u^{n+1/2})$$

$$+ b(w, p^{n+1}) = (w, f^{n+1}).$$

$$b(u^n, q) = 0$$

$w$  - shape function for velocity

$q$  - shape function for pressure.

$$c) \begin{bmatrix} M & K + G + R & G \\ G & 0 & 0 \end{bmatrix} \begin{bmatrix} u^{n+1} \\ u^{n+1/2} \\ p^{n+1} \end{bmatrix} = \begin{bmatrix} F + Mu^n \\ 0 \end{bmatrix}$$

$$F = \sum_e N_i \cdot f^{n+1}$$

$$M = \frac{1}{\Delta t} \sum_e N_i \cdot N_j$$

$$K = \sum_e \nabla N_i \cdot \nabla N_j \cdot \nu$$

$$C = \sum_e N_i \cdot N_j \cdot \nabla N_j$$

$$R = \sigma \sum_e N_i \cdot N_j$$

$$G = \sum_e N_i \cdot Q$$

d) For solving non-linear problems we can use the Picard method. below is the Picard's algorithm.

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$$A(u) u = b(u) \quad (\text{system to be solved}).$$

$$u = A(u)^{-1} b(u)$$

$$\Delta u^{k+1} = A(u^k)^{-1} b(u^k) - A(u^k) u^k$$

$$u^{k+1} = A(u^k)^{-1} b(u^k).$$

In our case:

$$A = \begin{bmatrix} M & K + G + R & G \\ G & 0 & 0 \end{bmatrix}$$

$$u = \begin{bmatrix} u \\ p \end{bmatrix}, \quad u = \begin{bmatrix} u^{n+1} \\ u^{n+1/2} \end{bmatrix}$$

$$b = \begin{bmatrix} F + Mu^n \\ 0 \end{bmatrix}$$

this system of equations will be solved on each iteration.

e) for  $Re = 100$ , both methods are behaving as expected, Picard's method converges linearly and N-R converges quadratically.

for  $Re = 1000$ , only the Picard's method is behaving as expected as linear convergence can be observed, but for the N-R method no convergence is observed but some oscillations away from the solution and i think this is so because at  $Re = 1000$  the flow is convection dominated and as such highly non-linear which ~~lead~~ might lead to formation of more vortices which causes the N-R method to fail. (for example this can be observed in the cavity flow where another vortex starts to form at the bottom corner of the domain).